Low Voltage Precision Adjustable Shunt Regulator

The TLV431A, B and C series are precision low voltage shunt regulators that are programmable over a wide voltage range of 1.24 V to 16 V. The TLV431A series features a guaranteed reference accuracy of $\pm 1.0\%$ at 25°C and $\pm 2.0\%$ over the entire industrial temperature range of -40°C to 85°C. The TLV431B series features higher reference accuracy of $\pm 0.5\%$ and $\pm 1.0\%$ respectively. For the TLV431C series, the accuracy is even higher. It is $\pm 0.2\%$ and $\pm 1.0\%$ respectively. These devices exhibit a sharp low current turn-on characteristic with a low dynamic impedance of 0.20 Ω over an operating current range of 100 μ A to 20 mA. This combination of features makes this series an excellent replacement for zener diodes in numerous applications circuits that require a precise reference voltage. When combined with an optocoupler, the TLV431A/B/C can be used as an error amplifier for controlling the feedback loop in isolated low output voltage (3.0 V to 3.3 V) switching power supplies. These devices are available in economical TO-92-3 and micro size TSOP-5 and SOT-23-3 packages.

Features

- Programmable Output Voltage Range of 1.24 V to 16 V
- Voltage Reference Tolerance ±1.0% for A Series, ±0.5% for B Series and ±0.2% for C Series
- Sharp Low Current Turn-On Characteristic
- Low Dynamic Output Impedance of 0.20Ω from $100 \mu A$ to 20 mA
- Wide Operating Current Range of 50 µA to 20 mA
- Micro Miniature TSOP-5, SOT-23-3 and TO-92-3 Packages
- SCV and NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC-Q100 Qualified and PPAP Capable
- These are Pb-Free and Halide-Free Devices

Applications

- Low Output Voltage (3.0 V to 3.3 V) Switching Power Supply Error Amplifier
- Adjustable Voltage or Current Linear and Switching Power Supplies
- Voltage Monitoring
- Current Source and Sink Circuits
- Analog and Digital Circuits Requiring Precision References
- Low Voltage Zener Diode Replacements

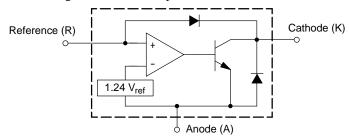
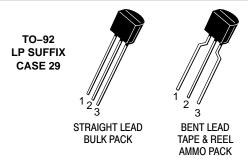


Figure 1. Representative Block Diagram



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TSOP-5 SN SUFFIX CASE 483



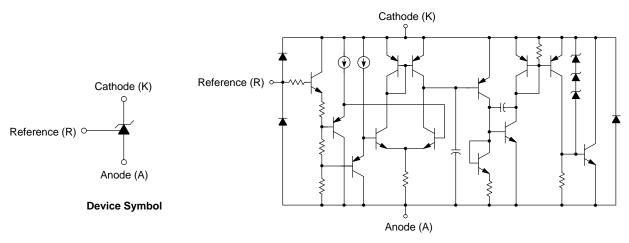
SOT-23 SN1 SUFFIX CASE 318

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 14 of this data sheet.

DEVICE MARKING INFORMATION AND PIN CONNECTIONS

See general marking information in the device marking section on page 13 of this data sheet.



The device contains 13 active transistors.

Figure 2. Representative Device Symbol and Schematic Diagram

MAXIMUM RATINGS (Full operating ambient temperature range applies, unless otherwise noted)

Rating	Symbol	Value	Unit	
Cathode to Anode Voltage		V_{KA}	18	V
Cathode Current Range, Continuous		I _K	-20 to 25	mA
Reference Input Current Range, Continuous		I _{ref}	-0.05 to 10	mA
Thermal Characteristics LP Suffix Package, TO–92–3 Package Thermal Resistance, Junction–to–Ambient Thermal Resistance, Junction–to–Case SN Suffix Package, TSOP–5 Package Thermal Resistance, Junction–to–Ambient SN1 Suffix Package, SOT–23–3 Package Thermal Resistance, Junction–to–Ambient		R _θ ja R _θ jc R _θ ja R _θ ja	178 83 226 491	°C/W
Operating Junction Temperature		TJ	150	°C
Operating Ambient Temperature Range	TLV431x NCV431, SCV431B	T _A	- 40 to 85 - 40 to 125	°C
Storage Temperature Range		T _{stg}	-65 to 150	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

NOTE: This device series contains ESD protection and exceeds the following tests:

Human Body Model 2000 V per JEDEC JESD22-A114F, Machine Model Method 200 V per JEDEC JESD22-A115C,

Charged Device Method 1000 V per JEDEC JESD22–C101E. This device contains latch–up protection and exceeds ± 100 mA per JEDEC standard JESD78.

$$P_D = \frac{T_{J(max)} - T_A}{R_{\theta,JA}}$$

RECOMMENDED OPERATING CONDITIONS

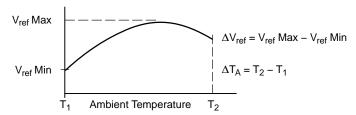
Condition	Symbol	Min	Max	Unit
Cathode to Anode Voltage	V_{KA}	V _{ref}	16	V
Cathode Current	I _K	0.1	20	mA

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

ELECTRICAL CHARACTERISTICS (T_A = 25°C unless otherwise noted)

		TLV431A		TLV431B				
Characteristic	Symbol	Min	Тур	Max	Min	Тур	Max	Unit
Reference Voltage (Figure 3) $(V_{KA} = V_{ref}, I_K = 10 \text{ mA}, T_A = 25^{\circ}\text{C})$ $(T_A = T_{low} \text{ to } T_{high}, \text{ Note 1})$		1.228 1.215	1.240	1.252 1.265	1.234 1.228	1.240	1.246 1.252	V
Reference Input Voltage Deviation Over Temperature (Figure 3) $(V_{KA} = V_{ref}, I_{K} = 10 \text{ mA}, T_{A} = T_{low} \text{ to } T_{high}, \text{ Notes } 1, 2, 3)$		-	7.2	20	-	7.2	20	mV
Ration of Reference Input Voltage Change to Cathode Voltage Change (Figure 4) (V _{KA} = V _{ref} to 16 V, I _K = 10 mA)		_	-0.6	-1.5	-	-0.6	-1.5	$\frac{\text{mV}}{\text{V}}$
Reference Terminal Current (Figure 4) (I _K = 10 mA, R1 = 10 k Ω , R2 = open)	I _{ref}	-	0.15	0.3	_	0.15	0.3	μА
Reference Input Current Deviation Over Temperature (Figure 4) ΔI_{re} ($I_K = 10$ mA, R1 = 10 k Ω , R2 = open, Notes 1, 2, 3)		-	0.04	0.08	-	0.04	0.08	μΑ
Minimum Cathode Current for Regulation (Figure 3)	I _{K(min})	-	30	80	-	30	80	μΑ
Off–State Cathode Current (Figure 5) $ (V_{KA} = 6.0 \text{ V}, V_{ref} = 0) $ $ (V_{KA} = 16 \text{ V}, V_{ref} = 0) $	I _{K(off)}	_ _	0.01 0.012	0.04 0.05		0.01 0.012	0.04 0.05	μΑ
Dynamic Impedance (Figure 3) $(V_{KA} = V_{ref}, I_K = 0.1 \text{ mA} \text{ to } 20 \text{ mA}, f \le 1.0 \text{ kHz}, \text{ Note 4})$	Z _{KA}	-	0.25	0.4	-	0.25	0.4	Ω

- 1. Ambient temperature range: $T_{low} = -40^{\circ}C$, $T_{high} = 85^{\circ}C$. 2. Guaranteed but not tested.
- 3. The deviation parameters ΔV_{ref} and ΔI_{ref} are defined as the difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



The average temperature coefficient of the reference input voltage, αV_{ref} is defined as:

$$\alpha V_{ref} \left(\frac{ppm}{^{\circ}C} \right) = \frac{\left(\frac{(\Delta V_{ref})}{V_{ref} \left(T_{A} = 25^{\circ}C \right)} \times 10^{6} \right)}{\Delta T_{A}}$$

 αV_{ref} can be positive or negative depending on whether V_{ref} Min or V_{ref} Max occurs at the lower ambient temperature, refer to Figure 8. Example: $\Delta V_{ref} = 7.2 \text{ mV}$ and the slope is positive,

$$V_{ref} @ 25^{\circ}C = 1.241 \text{ V}$$

 $\Delta T_A = 125^{\circ}C$

$$\alpha V_{ref} \left(\frac{ppm}{^{\circ}C} \right) = \frac{0.0072}{1.241} \times 10^{6} = 46 \text{ ppm/}^{\circ}C$$

4. The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{K}}$$

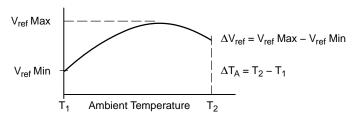
When the device is operating with two external resistors, R1 and R2, (refer to Figure 4) the total dynamic impedance of the circuit is given by:

$$|Z_{KA}'| = |Z_{KA}| \times \left(1 + \frac{R1}{R2}\right)$$

ELECTRICAL CHARACTERISTICS (T_A = 25°C unless otherwise noted)

	TLV431C			;	
Characteristic	Symbol	Min	Тур	Max	Unit
Reference Voltage (Figure 3) $ (V_{KA} = V_{ref}, I_K = 10 \text{ mA}, T_A = 25^{\circ}\text{C}) $ $ (T_A = T_{low} \text{ to } T_{high}, \text{ Note 5}) $	V _{ref}	1.237 1.228	1.240	1.243 1.252	V
Reference Input Voltage Deviation Over Temperature (Figure 3) $(V_{KA} = V_{ref}, I_K = 10 \text{ mA}, T_A = T_{low} \text{ to } T_{high}, \text{ Notes 5, 6, 7)}$	ΔV_{ref}	_	7.2	2.0	mV
Ration of Reference Input Voltage Change to Cathode Voltage Change (Figure 4) $(V_{KA} = V_{ref} \text{ to } 16 \text{ V}, I_K = 10 \text{ mA})$	$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	-	-0.6	-1.5	$\frac{\text{mV}}{\text{V}}$
Reference Terminal Current (Figure 4) (I _K = 10 mA, R1 = 10 k Ω , R2 = open)	I _{ref}	-	0.15	0.3	μΑ
Reference Input Current Deviation Over Temperature (Figure 4) (I _K = 10 mA, R1 = 10 k Ω , R2 = open, Notes 5, 6, 7)	ΔI_{ref}	-	0.04	0.08	μΑ
Minimum Cathode Current for Regulation (Figure 3)	I _{K(min})	-	30	80	μΑ
Off–State Cathode Current (Figure 5) (V _{KA} = 6.0 V, V _{ref} = 0) (V _{KA} = 16 V, V _{ref} = 0)	I _{K(off)}	-	0.01 0.012	0.04 0.05	μΑ
Dynamic Impedance (Figure 3) $(V_{KA} = V_{ref}, I_K = 0.1 \text{ mA to } 20 \text{ mA, } f \leq 1.0 \text{ kHz, Note } 8)$	Z _{KA}	_	0.25	0.4	Ω

- 5. Ambient temperature range: $T_{low} = -40^{\circ}C$, $T_{high} = 85^{\circ}C$. 6. Guaranteed but not tested.
- The deviation parameters ΔV_{ref} and ΔI_{ref} are defined as the difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



The average temperature coefficient of the reference input voltage, αV_{ref} is defined as:

$$\alpha V_{ref} \, \left(\frac{ppm}{^{\circ}C} \right) = \frac{\left(\frac{(\Delta V_{ref})}{V_{ref} \, (T_{A} = 25^{\circ}C)} \times \, 10^{6} \right)}{\Delta T_{A}}$$

 αV_{ref} can be positive or negative depending on whether V_{ref} Min or V_{ref} Max occurs at the lower ambient temperature, refer to Figure 8. Example: $\Delta V_{ref} = 7.2 \text{ mV}$ and the slope is positive,

$$V_{ref}$$
 @ 25°C = 1.241 V $\Delta T_A = 125$ °C

$$\alpha V_{ref} \left(\frac{ppm}{{}^{\circ}C} \right) = \frac{0.0072}{1.241} \times 10^{6} = 46 \text{ ppm/}^{\circ}C$$

8. The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{K}}$$

When the device is operating with two external resistors, R1 and R2, (refer to Figure 4) the total dynamic impedance of the circuit is given by:

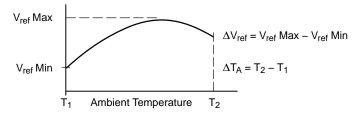
$$|Z_{KA}'| = |Z_{KA}| \times (1 + \frac{R1}{R2})$$

ELECTRICAL CHARACTERISTICS (T_A = 25°C unless otherwise noted)

		ı	ICV431	4	
Characteristic	Symbol	Min	Тур	Max	Unit
Reference Voltage (Figure 3) $ (V_{KA} = V_{ref}, I_K = 10 \text{ mA}, T_A = 25^{\circ}\text{C}) $ $ (T_A = -40^{\circ}\text{C to }85^{\circ}\text{C}) $ $ (T_A = -40^{\circ}\text{C to }125^{\circ}\text{C}) $	V _{ref}	1.228 1.215 1.211	1.240 - -	1.252 1.265 1.265	V
Reference Input Voltage Deviation Over Temperature (Figure 3) $ (V_{KA} = V_{ref}, I_{K} = 10 \text{ mA}, T_{A} = -40^{\circ}\text{C to } 85^{\circ}\text{C}, \text{Notes } 9, 10) \\ (V_{KA} = V_{ref}, I_{K} = 10 \text{ mA}, T_{A} = -40^{\circ}\text{C to } 125^{\circ}\text{C}, \text{Notes } 9, 10) $	ΔV_{ref}	_ _	7.2 7.2	20 24	mV
Ration of Reference Input Voltage Change to Cathode Voltage Change (Figure 4) $(V_{KA} = V_{ref} \text{ to 16 V}, I_{K} = 10 \text{ mA})$	$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	_	-0.6	-1.5	$\frac{mV}{V}$
Reference Terminal Current (Figure 4) (I _K = 10 mA, R1 = 10 k Ω , R2 = open)	I _{ref}	_	0.15	0.3	μΑ
Reference Input Current Deviation Over Temperature (Figure 4) $ (I_K=10 \text{ mA}, R1=10 \text{ k}\Omega, R2=\text{open}, T_A=-40^{\circ}\text{C to } 85^{\circ}\text{C}, \text{Notes } 9, 10) \\ (I_K=10 \text{ mA}, R1=10 \text{ k}\Omega, R2=\text{open}, T_A=-40^{\circ}\text{C to } 125^{\circ}\text{C}, \text{Notes } 9, 10) $	$\Delta I_{ m ref}$	_ _	0.04	0.08 0.10	μΑ
Minimum Cathode Current for Regulation (Figure 3)	I _{K(min})	-	30	80	μΑ
Off–State Cathode Current (Figure 5) $ (V_{KA} = 6.0 \text{ V}, V_{ref} = 0) $ $ (V_{KA} = 16 \text{ V}, V_{ref} = 0) $	I _{K(off)}	_ _	0.01 0.012	0.04 0.05	μΑ
Dynamic Impedance (Figure 3) $(V_{KA} = V_{ref}, I_K = 0.1 \text{mA to } 20 \text{mA}, f \leq 1.0 \text{kHz}, \text{Note } 11)$	Z _{KA}	_	0.25	0.4	Ω

9. Guaranteed but not tested.

^{10.} The deviation parameters ΔV_{ref} and ΔI_{ref} are defined as the difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



The average temperature coefficient of the reference input voltage, αV_{ref} is defined as:

$$\alpha V_{ref} \left(\frac{ppm}{^{\circ}C} \right) = \frac{\left(\frac{(\Delta V_{ref})}{V_{ref} (T_{A} = 25^{\circ}C)} \times 10^{6} \right)}{\Delta T_{A}}$$

 αV_{ref} can be positive or negative depending on whether V_{ref} Min or V_{ref} Max occurs at the lower ambient temperature, refer to Figure 8. Example: $\Delta V_{ref} = 7.2 \text{ mV}$ and the slope is positive,

$$V_{ref}$$
 @ 25°C = 1.241 V $\Delta T_{\Delta} = 125$ °C

$$\Delta T_A = 125^{\circ}C$$

$$\alpha V_{ref} \left(\frac{ppm}{^{\circ}C} \right) = \frac{\frac{0.0072}{1.241} \times 10^{6}}{125} = 46 \text{ ppm}/^{\circ}C$$

11. The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{K}}$$

When the device is operating with two external resistors, R1 and R2, (refer to Figure 4) the total dynamic impedance of the circuit is given by:

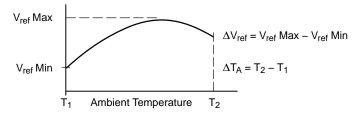
$$|Z_{KA}'| = |Z_{KA}| \times (1 + \frac{R1}{R2})$$

ELECTRICAL CHARACTERISTICS (T_A = 25°C unless otherwise noted)

		SCV431B, NCV431B			
Characteristic	Symbol	Min	Тур	Max	Unit
Reference Voltage (Figure 3) $ (V_{KA} = V_{ref}, I_K = 10 \text{ mA}, T_A = 25^{\circ}\text{C}) $ $ (T_A = -40^{\circ}\text{C to } 85^{\circ}\text{C}) $ $ (T_A = -40^{\circ}\text{C to } 125^{\circ}\text{C}) $	V _{ref}	1.234 1.228 1.224	1.240 - -	1.246 1.252 1.252	V
Reference Input Voltage Deviation Over Temperature (Figure 3) $ (V_{KA} = V_{ref}, I_{K} = 10 \text{ mA}, T_{A} = -40^{\circ}\text{C to } 85^{\circ}\text{C}, \text{ Notes } 9, 10) \\ (V_{KA} = V_{ref}, I_{K} = 10 \text{ mA}, T_{A} = -40^{\circ}\text{C to } 125^{\circ}\text{C}, \text{ Notes } 9, 10) $	ΔV_{ref}	- -	7.2 7.2	20 24	mV
Ration of Reference Input Voltage Change to Cathode Voltage Change (Figure 4) $(V_{KA} = V_{ref} \text{ to 16 V}, I_{K} = 10 \text{ mA})$		-	-0.6	-1.5	$\frac{\text{mV}}{\text{V}}$
Reference Terminal Current (Figure 4) ($I_K = 10 \text{ mA}, R1 = 10 \text{ k}\Omega, R2 = \text{open}$)	I _{ref}	-	0.15	0.3	μΑ
Reference Input Current Deviation Over Temperature (Figure 4) ($I_K = 10 \text{ mA}$, $R1 = 10 \text{ k}\Omega$, $R2 = \text{open}$, $T_A = -40^{\circ}\text{C}$ to 85°C, Notes 12, 13) ($I_K = 10 \text{ mA}$, $R1 = 10 \text{ k}\Omega$, $R2 = \text{open}$, $T_A = -40^{\circ}\text{C}$ to 125°C, Notes 12, 13)		<u>-</u>	0.04	0.08 0.10	μΑ
Minimum Cathode Current for Regulation (Figure 3)	I _{K(min})	-	30	80	μΑ
Off–State Cathode Current (Figure 5) $(V_{KA} = 6.0 \text{ V}, V_{ref} = 0)$ $(V_{KA} = 16 \text{ V}, V_{ref} = 0)$		- -	0.01 0.012	0.04 0.05	μΑ
Dynamic Impedance (Figure 3) $(V_{KA}=V_{ref},I_{K}=0.1\text{mA}\text{to}20\text{mA},f\leq1.0\text{kHz},\text{Note}14)$	Z _{KA}	-	0.25	0.4	Ω

12. Guaranteed but not tested.

^{13.} The deviation parameters ΔV_{ref} and ΔI_{ref} are defined as the difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



The average temperature coefficient of the reference input voltage, αV_{ref} is defined as:

$$\alpha V_{ref} \, \left(\frac{ppm}{^{\circ}C} \right) = \frac{\left(\frac{(\Delta V_{ref})}{V_{ref} \, (T_{A} = 25^{\circ}C)} \times \, 10^{6} \right)}{\Delta T_{A}}$$

 αV_{ref} can be positive or negative depending on whether V_{ref} Min or V_{ref} Max occurs at the lower ambient temperature, refer to Figure 8. Example: $\Delta V_{ref} = 7.2$ mV and the slope is positive,

$$V_{ref} @ 25^{\circ}C = 1.241 \text{ V}$$

 $\Delta T_A = 125^{\circ}C$

$$\alpha V_{ref} \left(\frac{ppm}{{}^{\circ}C} \right) = \frac{0.0072}{1.241} \times 10^{6} = 46 \text{ ppm}/{}^{\circ}C$$

14. The dynamic impedance Z_{KA} is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{K}}$$

When the device is operating with two external resistors, R1 and R2, (refer to Figure 4) the total dynamic impedance of the circuit is given by:

$$|Z_{KA}'| = |Z_{KA}| \times (1 + \frac{R1}{R2})$$

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

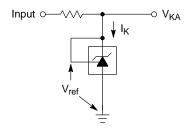
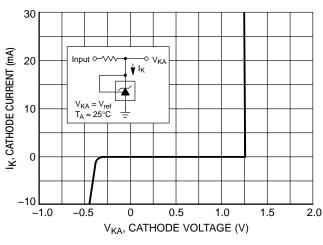


Figure 3. Test Circuit for V_{KA} = V_{ref}

Figure 4. Test Circuit for $V_{KA} > V_{ref}$

Figure 5. Test Circuit for I_{K(off)}

I_{K(off)}



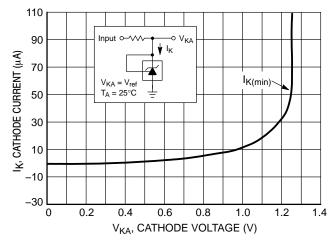


Figure 6. Cathode Current vs. Cathode Voltage

Figure 7. Cathode Current vs. Cathode Voltage

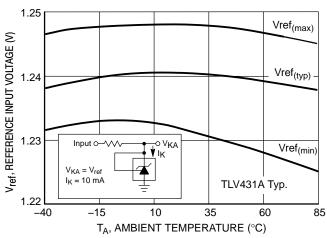


Figure 8. Reference Input Voltage versus

Ambient Temperature

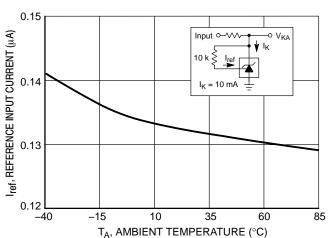
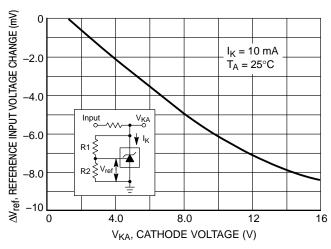


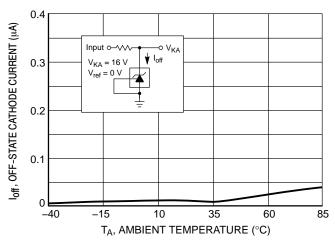
Figure 9. Reference Input Current versus
Ambient Temperature



4.0 (μA), CATHODE CURRENT (μA) **V** I_{off} V_{KA} = 16 V 3.0 = 0 V 2.0 $T_A = 25^{\circ}C$ 0 0 4.0 8.0 12 16 20 VKA, CATHODE VOLTAGE (V)

Figure 10. Reference Input Voltage Change versus Cathode Voltage

Figure 11. Off-State Cathode Current versus Cathode Voltage



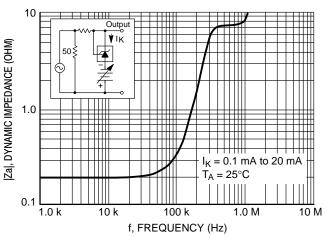
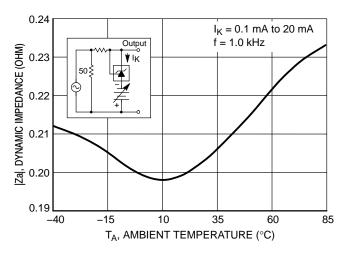


Figure 12. Off-State Cathode Current versus **Ambient Temperature**

Figure 13. Dynamic Impedance versus Frequency



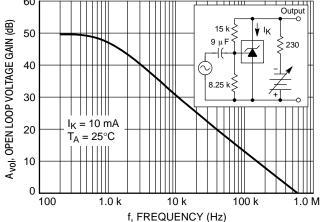


Figure 14. Dynamic Impedance versus **Ambient Temperature**

Figure 15. Open-Loop Voltage Gain versus Frequency

60

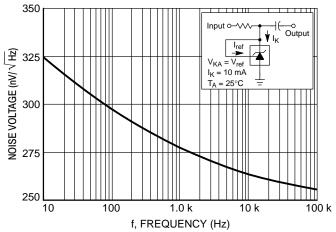


Figure 16. Spectral Noise Density

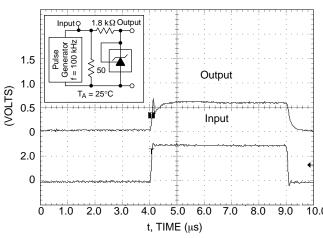


Figure 17. Pulse Response

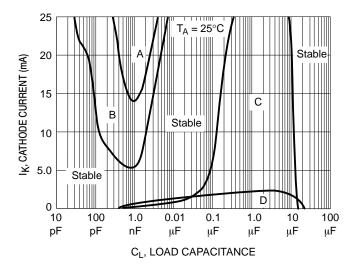
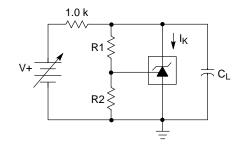


Figure 18. Stability Boundary Conditions



Unstable Regions	V _{KA} (V)	R1 (kΩ)	R2 (kΩ)
A, C	V_{ref}	0	8
B, D	5.0	30.4	10

Figure 19. Test Circuit for Figure 18

Stability

Figures 18 and 19 show the stability boundaries and circuit configurations for the worst case conditions with the load capacitance mounted as close as possible to the device. The required load capacitance for stable operation can vary depending on the operating temperature and capacitor

equivalent series resistance (ESR). Ceramic or tantalum surface mount capacitors are recommended for both temperature and ESR. The application circuit stability should be verified over the anticipated operating current and temperature ranges.

TYPICAL APPLICATIONS

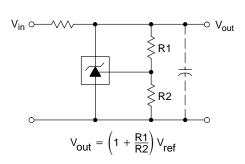


Figure 20. Shunt Regulator

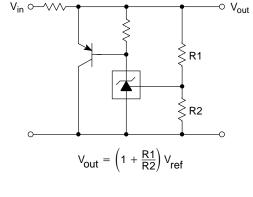


Figure 21. High Current Shunt Regulator

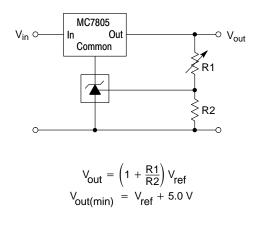


Figure 22. Output Control for a Three Terminal Fixed Regulator

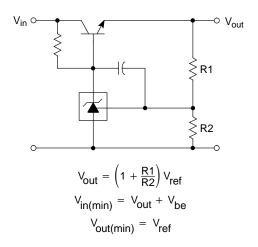


Figure 23. Series Pass Regulator

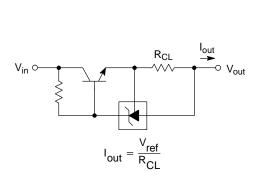


Figure 24. Constant Current Source

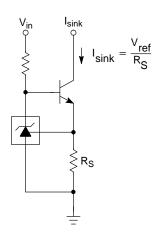


Figure 25. Constant Current Sink

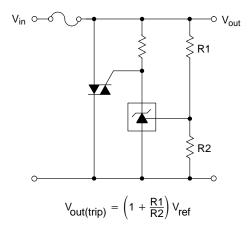


Figure 26. TRIAC Crowbar

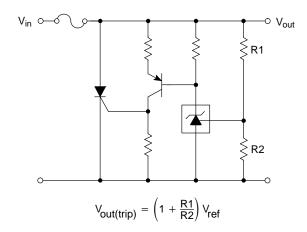
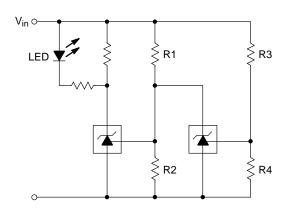


Figure 27. SCR Crowbar



L.E.D. indicator is 'ON' when V_{in} is between the upper and lower limits,

Lower limit =
$$\left(1 + \frac{R1}{R2}\right) V_{ref}$$

Upper limit = $\left(1 + \frac{R3}{R4}\right) V_{ref}$

Figure 28. Voltage Monitor

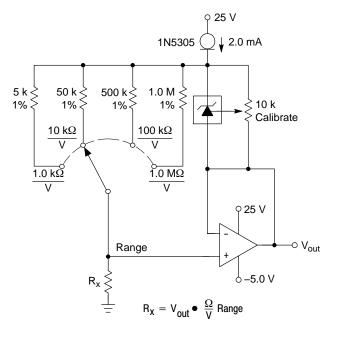


Figure 29. Linear Ohmmeter

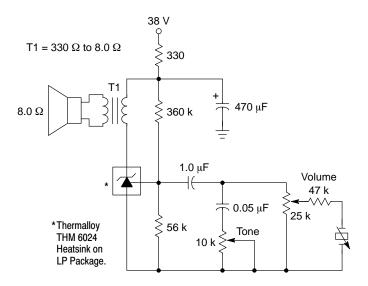


Figure 30. Simple 400 mW Phono Amplifier

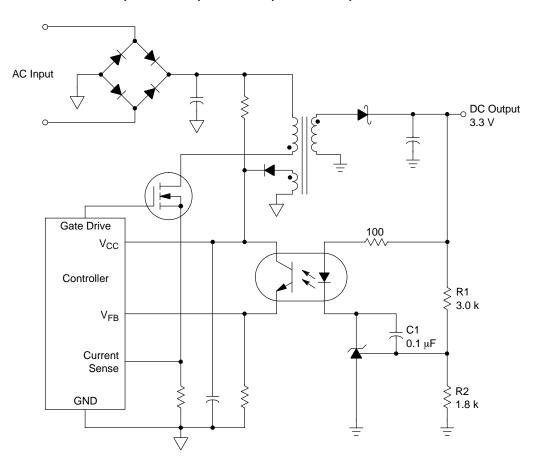
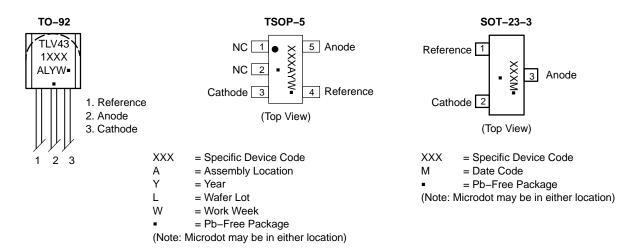


Figure 31. Isolated Output Line Powered Switching Power Supply

The above circuit shows the TLV431A/B/C as a compensated amplifier controlling the feedback loop of an isolated output line powered switching regulator. The output voltage is programmed to 3.3 V by the resistors values selected for R1 and R2. The minimum output voltage that can be programmed with this circuit is 2.64 V, and is limited by the sum of the reference voltage (1.24 V) and the forward drop of the optocoupler light emitting diode (1.4 V). Capacitor C1 provides loop compensation.

PIN CONNECTIONS AND DEVICE MARKING



ORDERING INFORMATION

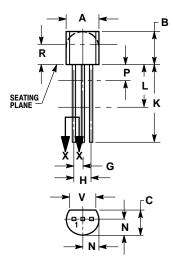
Device	Device Code	Package	Shipping [†]
TLV431ALPG	ALP	TO-92-3 (Pb-Free)	6000 / Box
TLV431ALPRAG	ALP	TO-92-3 (Pb-Free)	2000 / Tape & Reel
TLV431ALPREG	ALP	TO-92-3 (Pb-Free)	2000 / Tape & Reel
TLV431ALPRMG	ALP	TO-92-3 (Pb-Free)	2000 / Ammo Pack
TLV431ALPRPG	ALP	TO-92-3 (Pb-Free)	2000 / Ammo Pack
TLV431ASNT1G	RAA	TSOP-5 (Pb-Free, Halide-Free)	3000 / Tape & Reel
TLV431ASN1T1G	RAF	SOT-23-3 (Pb-Free, Halide-Free)	3000 / Tape & Reel
TLV431BLPG	BLP	TO-92-3 (Pb-Free)	6000 / Box
TLV431BLPRAG	BLP	TO-92-3 (Pb-Free)	2000 / Tape & Reel
TLV431BLPREG	BLP	TO-92-3 (Pb-Free)	2000 / Tape & Reel
TLV431BLPRMG	BLP	TO-92-3 (Pb-Free)	2000 / Ammo Pack
TLV431BLPRPG	BLP	TO-92-3 (Pb-Free)	2000 / Ammo Pack
TLV431BSNT1G	RAH	TSOP-5 (Pb-Free, Halide-Free)	3000 / Tape & Reel
TLV431BSN1T1G	RAG	SOT-23-3 (Pb-Free, Halide-Free)	3000 / Tape & Reel
TLV431CSN1T1G	AAN	SOT-23-3 (Pb-Free, Halide-Free)	3000 / Tape & Reel
SCV431BSN1T1G*	RAC	SOT-23-3 (Pb-Free, Halide-Free)	3000 / Tape & Reel
NCV431ASNT1G*	ACH	TSOP-5 (Pb-Free, Halide-Free)	3000 / Tape & Reel
NCV431BSNT1G*	AD6	TSOP-5 (Pb-Free, Halide-Free)	3000 / Tape & Reel

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

^{*}SCV, NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC-Q100 Qualified and PPAP Capable.

PACKAGE DIMENSIONS

TO-92 (TO-226) **LP SUFFIX** CASE 29-11 **ISSUE AN**

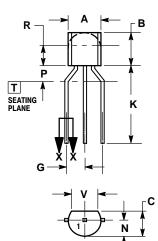


STRAIGHT LEAD **BULK PACK**



- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
 3. CONTOUR OF PACKAGE BEYOND DIMENSION R IS UNCONTROLLED.
 4. LEAD DIMENSION IS UNCONTROLLED IN P AND BEYOND DIMENSION K MINIMUM.

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.175	0.205	4.45	5.20
В	0.170	0.210	4.32	5.33
С	0.125	0.165	3.18	4.19
D	0.016	0.021	0.407	0.533
G	0.045	0.055	1.15	1.39
Н	0.095	0.105	2.42	2.66
J	0.015	0.020	0.39	0.50
K	0.500		12.70	
L	0.250		6.35	
N	0.080	0.105	2.04	2.66
Р		0.100		2.54
R	0.115		2.93	
v	0.135		3 //3	



BENT LEAD TAPE & REEL AMMO PACK

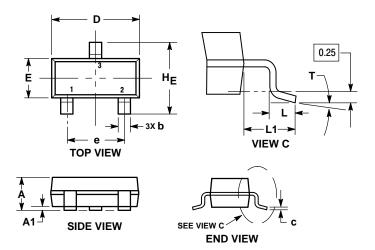


- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
 2. CONTROLLING DIMENSION: MILLIMETERS.
 3. CONTOUR OF PACKAGE BEYOND DIMENSION R IS UNCONTROLLED.
 4. LEAD DIMENSION IS UNCONTROLLED IN P AND BEYOND DIMENSION K MINIMUM.

	MILLIMETERS					
DIM	MIN	MAX				
Α	4.45	5.20				
В	4.32	5.33				
С	3.18	4.19				
D	0.40	0.54				
G	2.40	2.80				
J	0.39	0.50				
K	12.70					
N	2.04	2.66				
P	1.50	4.00				
R	2.93					
٧	3.43					

PACKAGE DIMENSIONS

SOT-23 (TO-236) CASE 318-08 **ISSUE AR**

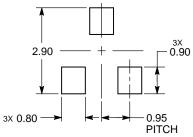


- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
 2. CONTROLLING DIMENSION: MILLIMETERS.
 3. MAXIMUM LEAD THICKNESS INCLUDES LEAD FINISH.
 MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS OF
 THE BASE MATERIAL.
 4. DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH,
 PROTRUSIONS, OR GATE BURRS.

	М	MILLIMETERS			INCHES		
DIM	MIN	NOM	MAX	MIN	NOM	MAX	
Α	0.89	1.00	1.11	0.035	0.039	0.044	
A1	0.01	0.06	0.10	0.000	0.002	0.004	
b	0.37	0.44	0.50	0.015	0.017	0.020	
С	0.08	0.14	0.20	0.003	0.006	0.008	
D	2.80	2.90	3.04	0.110	0.114	0.120	
Е	1.20	1.30	1.40	0.047	0.051	0.055	
е	1.78	1.90	2.04	0.070	0.075	0.080	
L	0.30	0.43	0.55	0.012	0.017	0.022	
L1	0.35	0.54	0.69	0.014	0.021	0.027	
ΗE	2.10	2.40	2.64	0.083	0.094	0.104	
Т	0°		10°	0°		10°	

RECOMMENDED SOLDERING FOOTPRINT*

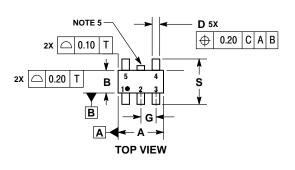


DIMENSIONS: MILLIMETERS

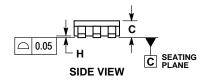
^{*}For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

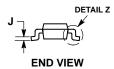
PACKAGE DIMENSIONS

TSOP-5 SN SUFFIX CASE 483 ISSUE M







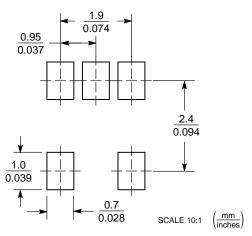


NOTES:

- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
 CONTROLLING DIMENSION: MILLIMETERS.
- CONTROLLING DIMENSION: MILLIMETERS.
 MAXIMUM LEAD THICKNESS INCLUDES LEAD FINISH THICKNESS. MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS OF BASE MATERIAL.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD FLASH, PROTRUSIONS, OR GATE BURRS. MOLD FLASH, PROTRUSIONS, OR GATE BURRS SHALL NOT EXCEED 0.15 PER SIDE. DIMENSION A.
- OPTIONAL CONSTRUCTION: AN ADDITIONAL TRIMMED LEAD IS ALLOWED IN THIS LOCATION. TRIMMED LEAD NOT TO EXTEND MORE THAN 0.2 FROM BODY.

TROW BODT.					
	MILLIMETERS				
DIM	MIN	MAX			
Α	2.85	3.15			
В	1.35	1.65			
C	0.90	1.10			
D	0.25	0.50			
G	0.95	BSC			
Н	0.01	0.10			
J	0.10	0.26			
K	0.20	0.60			
М	0 °	10°			
s	2.50	3.00			

SOLDERING FOOTPRINT*



*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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